

DS-210: PROGRAMMING FOR DATA SCIENCE

LECTURE 35

- 1. ERROR HANDLING IN RUST
- 2. ALGORITHM DESIGN: DYNAMIC PROGRAMMING



ERROR HANDLING IN RUST

Two basic options:

- terminate when an error occurs: macro panic!(...)
- pass information about an error: enum Result<T, E>



MACRO panic!(...)

- Use for unrecoverable errors
- Terminates the application





MACRO panic! (...)

- Use for unrecoverable errors
- Terminates the application

```
In [2]: fn divide(a:u32, b:u32) -> u32 {
    if b == 0 {
        panic!("I'm sorry, Dave. I'm afraid I can't do that.");
    }
    a/b
}
```





MACRO panic!(...)

- Use for unrecoverable errors
- Terminates the application

```
In [2]:
    fn divide(a:u32, b:u32) -> u32 {
        if b == 0 {
            panic!("I'm sorry, Dave. I'm afraid I can't do that.");
        }
        a/b
    }
```

```
In [3]: divide(20,7)
Out[3]: 2
```





MACRO panic!(...)

- Use for unrecoverable errors
- Terminates the application

```
In [2]: fn divide(a:u32, b:u32) -> u32 {
            if b == 0 {
                panic!("I'm sorry, Dave. I'm afraid I can't do that.");
            a/b
                                                                        In [4]: divide(20,0)
In [3]: divide(20,7)
Out[3]: 2
                                                                                 thread '<unnamed>' panicked at 'I'm sorry, Dave. I'm af
                                                                                 raid I can't do that.', src/lib.rs:4:9
                                                                                 stack backtrace:
                                                                                    0: std::panicking::begin panic
                                                                                    1: run user code 3
                                                                                    2: evcxr::runtime::Runtime::run loop
                                                                                    3: evcxr::runtime::runtime hook
                                                                                    4: evcxr jupyter::main
                                                                                 note: Some details are omitted, run with `RUST BACKTRAC
                                                                                 E=full` for a verbose backtrace.
                                                                                 Segmentation fault.
                                                                                    0: evcxr::runtime::Runtime::install_crash_handlers::
                                                                                 segfault handler
                                                                                    1: <unknown>
                                                                                    2: mi free generic
                                                                                    3: alloc::alloc::dealloc
                                                                                              at /rustc/9d1b2106e23b1abd32fce1f17267604a
                                                                                 5102f57a/library/alloc/src/alloc.rs:105:14
                                                                                       <alloc::alloc::Global as core::alloc::Allocator</pre>
```

>::deallocate



```
enum Result<T,E> {
    Ok(T),
    Err(E),
}
```

- return a result
- or information about an encountered error





```
enum Result<T,E> {
    Ok(T),
    Err(E),
}
```

- return a result
- or information about an encountered error

```
In [5]: fn divide(a:u32, b:u32) -> Result<u32, &'static str> {
    if b != 0 {
        Ok(a / b)
    } else {
        Err("Division by zero")
    }
}
```





```
enum Result<T,E> {
    Ok(T),
    Err(E),
}
```

- return a result
- or information about an encountered error

```
In [5]: fn divide(a:u32, b:u32) -> Result<u32, &'static str> {
    if b != 0 {
        Ok(a / b)
    } else {
        Err("Division by zero")
    }
}
In [6]: divide(20,7)

In [7]: divide(20,0)

Out[6]: Ok(2)

Out[7]: Err("Division by zero")
```





```
enum Result<T,E> {
    Ok(T),
    Err(E),
}
```

- return a result
- or information about an encountered error

```
In [5]: fn divide(a:u32, b:u32) -> Result<u32, &'static str> {
    if b != 0 {
        Ok(a / b)
    } else {
        Err("Division by zero")
    }
}
In [6]: divide(20,7)

In [7]: divide(20,0)

Out[6]: Ok(2)

Out[7]: Err("Division by zero")
```

- Useful when the error best handled somewhere else
- Example: input/output subroutines in the standard library





COMMON PATTERN: PROPAGATING ERRORS

- We are interested in the positive outcome: t in 0k(t)
- But if an error occurs, we want to propagate it
- This can be handled using match statements

```
In [8]:
// compute a/b + c/d
fn calculate(a:u32, b:u32, c:u32, d:u32) -> Result<u32, &'static str> {
    let first = match divide(a,b) {
        Ok(t) => t,
        Err(e) => return Err(e),
    };
    let second = match divide(c,d) {
        Ok(t) => t,
        Err(e) => return Err(e),
    };
    Ok(first + second)
}
```

4.1



COMMON PATTERN: PROPAGATING ERRORS

- We are interested in the positive outcome: t in 0k(t)
- But if an error occurs, we want to propagate it
- This can be handled using match statements

```
In [8]: // compute a/b + c/d
fn calculate(a:u32, b:u32, c:u32, d:u32) -> Result<u32, &'static str> {
    let first = match divide(a,b) {
        Ok(t) => t,
        Err(e) => return Err(e),
    };
    let second = match divide(c,d) {
        Ok(t) => t,
        Err(e) => return Err(e),
    };
    Ok(first + second)
}

In [9]: calculate(16,4,18,3)

In [10]: calculate(16,0,18,3)

Out[9]: Ok(10)
Out[10]: Err("Division by zero")
```





THE QUESTION MARK SHORTCUT

- Place ? after an expression that returns Result<T, E>
- This will:
 - give the content of 0k(t)
 - or return Err(e) from the encompassing function



THE QUESTION MARK SHORTCUT

- Place ? after an expression that returns Result<T, E>
- This will:
 - give the content of 0k(t)
 - or return Err(e) from the encompassing function

```
In [11]: // compute a/b + c/d
fn calculate(a:u32, b:u32, c:u32, d:u32) -> Result<u32, &'static str> {
    Ok(divide(a,b)? + divide(c,d)?)
}
```





THE QUESTION MARK SHORTCUT

- Place ? after an expression that returns Result<T, E>
- This will:
 - give the content of 0k(t)
 - or return Err(e) from the encompassing function





1. ERROR HANDLING IN RUST

2. ALGORITHM DESIGN: DYNAMIC PROGRAMMING



BIG PICTURE: REST OF THIS LECTURE AND NEXT

Review a few approaches to algorithm design:

- dynamic programming
- greedy approach
- divide and conquer



HOMEWORK 9: BEST DECISION TREE FOR A CLASSIFICATION PROBLEM

Input: set of *n* labelled points (x_i, z_i) , where $x_i \in \mathbb{R}$ and $z_i \in \{0, 1\}$

Goal: find decision tree with L leaves and highest accuracy on the input set



How to solve it?





How to solve it?

Two-leaf decision tree: if x < T, output α , else output $(1 - \alpha)$





How to solve it?

Two-leaf decision tree: if x < T, output α , else output $(1 - \alpha)$

Two parameters: T and α

- suffices to try $T = x_i$ for all x_i 's and $\alpha \in \{0, 1\}$
- at most 2n options





How to solve it?

Two-leaf decision tree: if x < T, output α , else output $(1 - \alpha)$

Two parameters: T and α

- suffices to try $T = x_i$ for all x_i 's and $\alpha \in \{0, 1\}$
- at most 2n options

Algorithms:

- Simple: evaluate accuracy for each T and $\alpha \Rightarrow O(n^2)$ time
- More sophisticated: sort points, move the threshold for each α updating accuracies $\Rightarrow O(n \log n)$ time









How do decision trees with at most L leaves partition the line?





How do decision trees with at most L leaves partition the line?

- ullet at most L line segments: prediction fixed to 0 or 1 for each
- $\binom{n}{L-1} = O\left(n^{L-1}\right)$ thresholds configurations to consider
- test each: $O(n^L)$ -time algorithm



How do decision trees with at most L leaves partition the line?

- at most L line segments: prediction fixed to 0 or 1 for each
- $\binom{n}{L-1} = O(n^{L-1})$ thresholds configurations to consider
- test each: $O(n^L)$ -time algorithm

OUR GOAL: MUCH FASTER ALGORITHM





DEFINE SUBPROBLEMS

Simplifying assumption: $x_1 < x_2 < ... < x_n$



DEFINE SUBPROBLEMS

Simplifying assumption: $x_1 < x_2 < ... < x_n$

M[l,k] = the minimum number of mistakes, when classifying the first k points, using at most l ranges

- $l \in \{1, ..., L\}$
- $k \in \{1, ..., n\}$





DEFINE SUBPROBLEMS

Simplifying assumption: $x_1 < x_2 < \ldots < x_n$

M[l,k] = the minimum number of mistakes, when classifying the first k points, using at most l ranges

- $l \in \{1, ..., L\}$
- $k \in \{1, ..., n\}$

M[L, n] will give the best accuracy





M[l,k] = the minimum number of mistakes, when classifying the first k points, using at most l ranges

- $l \in \{1, ..., L\}$
- $k \in \{1, ..., n\}$



M[l,k] = the minimum number of mistakes, when classifying the first k points, using at most l ranges

- $l \in \{1, ..., L\}$
- $k \in \{1, ..., n\}$

ONE LABEL PREDICTIONS ON $\{x_k : i \le k \le j\}$

- Define S[i, j] = number of mispredictions for one label classifiers on this set
- S[i, j] minimum of the numbers of 0 and 1 labels on this set





M[l,k] = the minimum number of mistakes, when classifying the first k points, using at most l ranges

- $l \in \{1, ..., L\}$
- $k \in \{1, ..., n\}$

ONE LABEL PREDICTIONS ON $\{x_k : i \le k \le j\}$

- Define S[i, j] = number of mispredictions for one label classifiers on this set
- S[i, j] minimum of the numbers of 0 and 1 labels on this set

COMPUTE M[1, k] FOR ALL k

- $M[1, k] \leftarrow S[1, k]$
- O(n) time overall





M[l,k] = the minimum number of mistakes, when classifying the first k points, using at most l ranges

- $l \in \{1, ..., L\}$
- $k \in \{1, ..., n\}$

S[i, j] =the minimum number of mistakes, when classifying points $\{x_k : i \le k \le j\}$ with one range



M[l,k] = the minimum number of mistakes, when classifying the first k points, using at most l ranges

- $l \in \{1, ..., L\}$
- $k \in \{1, ..., n\}$

S[i,j] =the minimum number of mistakes, when classifying points $\{x_k : i \le k \le j\}$ with one range

COMPUTE M[l, k] FOR $l \ge 2$ AND ALL k

$$M[l,k] \leftarrow \min_{i=\{1,\ldots,k\}} (M[l-1,i] + S[i+1,k])$$









• Computing S[i, j] for all i and j: $O(n^2)$





- Computing S[i, j] for all i and j: $O(n^2)$
- Computing M[l+1,i] for all i from M[l,i]: $O(n^2)$





- Computing S[i, j] for all i and j: $O(n^2)$
- Computing M[l+1,i] for all i from M[l,i]: $O(n^2)$
- Total running time: $O(L) \cdot O(n^2) = O(Ln^2)$
- Much better than the more straightforward $O(n^L)$





RECONSTRUCTING THE SOLUTION

- This gives us M[L, n] = the minimum number of mistakes overall
- How to get the best solution, not just the best cost?





RECONSTRUCTING THE SOLUTION

- This gives us M[L, n] = the minimum number of mistakes overall
- How to get the best solution, not just the best cost?

Iteratively:

- Start from M[L, n]
- Find i the best M[L-1,i] + S[i+1,n]
- Label $\{x_{i+1}, \dots, x_n\}$ with the better of 0 and 1
- Continue with M[L-1, i]
- ...





DYNAMIC PROGRAMMING IN GENERAL

- Define a small number of subproblems that are
 - sufficient to solve the general problem
 - helpful to solve each other



DYNAMIC PROGRAMMING IN GENERAL

- Define a small number of subproblems that are
 - sufficient to solve the general problem
 - helpful to solve each other

The most classic example: edit distance

- minimum number of edits to turn one string into another
- edits: deletions, insertions, substitutions
- correcting spelling mistakes: how far are two words?

Can you solve it?

